

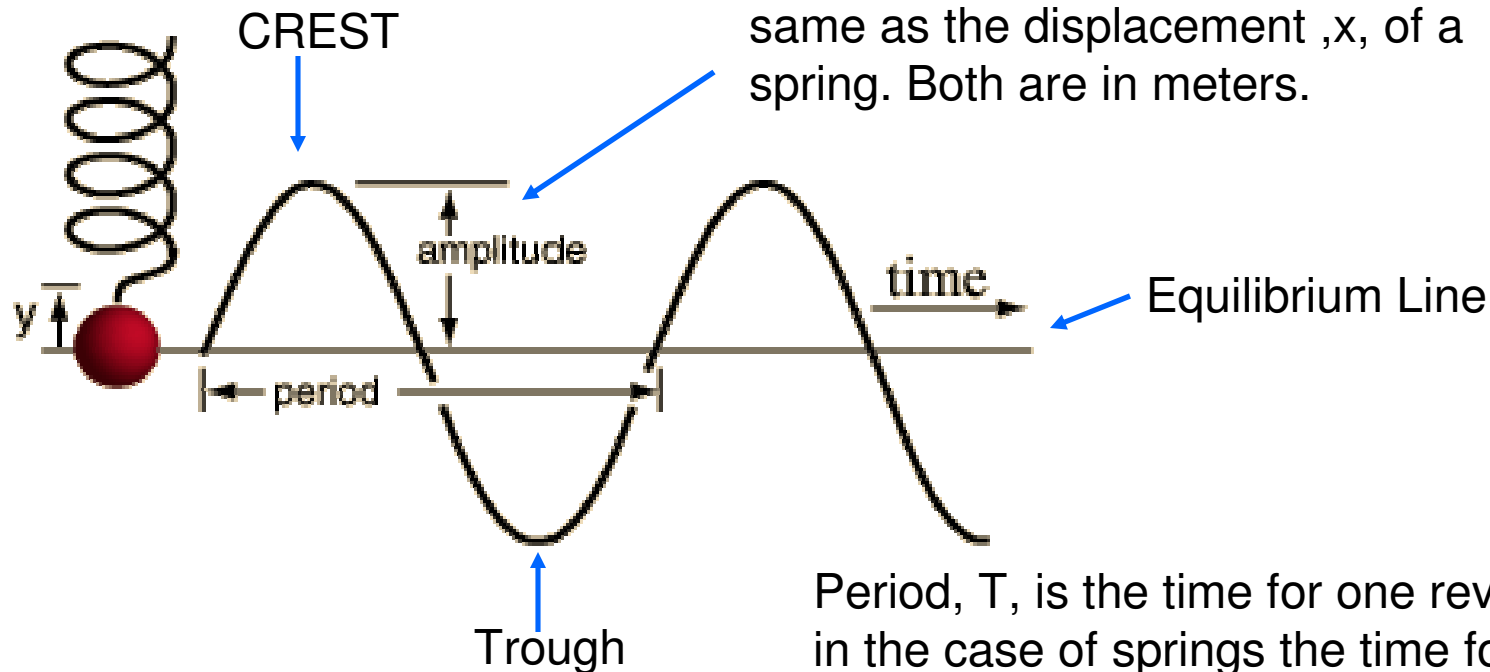
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# Harmonic Motion

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AP Physics C

# Springs are like Waves and Circles



The amplitude,  $A$ , of a wave is the same as the displacement,  $x$ , of a spring. Both are in meters.

**$T_s = \text{sec/cycle}$** . Let's assume that the wave crosses the equilibrium line in one second intervals.  $T = 3.5 \text{ seconds} / 1.75 \text{ cycles}$ .  **$T = 2 \text{ sec}$** .

Period,  $T$ , is the time for one revolution or in the case of springs the time for ONE COMPLETE oscillation (One crest and trough). Oscillations could also be called vibrations and **cycles**. In the wave above we have 1.75 cycles or waves or vibrations or oscillations.

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# Frequency

The **FREQUENCY** of a wave is the inverse of the PERIOD. That means that the frequency is the #cycles per sec. The commonly used unit is HERTZ(HZ).

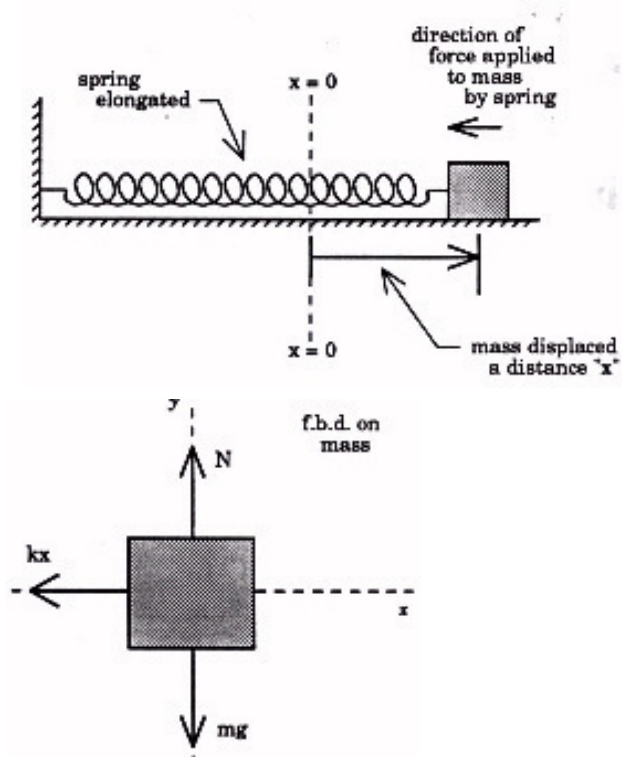
$$\text{Period} = T = \frac{\text{seconds}}{\text{cycles}} = \frac{3.5s}{1.75\text{cyc}} = 2s$$

$$\text{Frequency} = f = \frac{\text{cycles}}{\text{seconds}} = \frac{1.75\text{cyc}}{3.5\text{sec}} = 0.5 \text{ c/s} = 0.5\text{Hz}$$

$$T = \frac{1}{f} \quad f = \frac{1}{T}$$

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# Recall: Hooke's Law



Here is what we want to do: **DERIVE AN EXPRESSION THAT DEFINES THE DISPLACEMENT FROM EQUILIBRIUM OF THE SPRING IN TERMS OF TIME.**

$$F_{spring} = -kx \quad F_{Net} = ma$$

$$-kx = ma \quad a = \frac{d^2x}{dt}$$

$$-kx = m \frac{d^2x}{dt}$$

$$\frac{d^2x}{dt} + \left(\frac{k}{m}\right)x = 0$$

**WHAT DOES THIS MEAN? THE SECOND DERIVATIVE OF A FUNCTION THAT IS ADDED TO A CONSTANT TIMES ITSELF IS EQUAL TO ZERO.**

**What kind of function will ALWAYS do this?**

# A SINE FUNCTION!

$$x(t) = A \sin(\omega t + \phi)$$

$A = \text{amplitude}$

$\omega = \text{angular\_frequency}$

$\phi = \text{Phase\_Shift}$

$$x(t) = A \sin(\omega t + \phi)$$

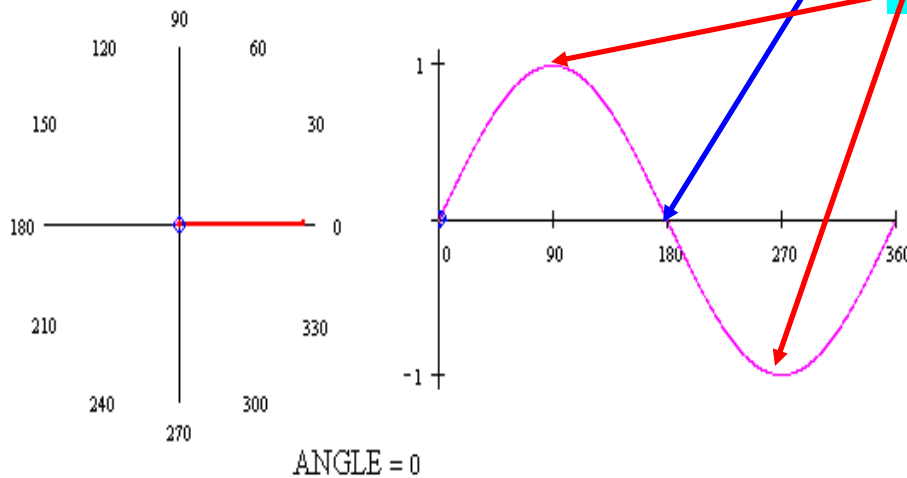
$$v(t) = \omega A \cos(\omega t + \phi)$$

$$a(t) = -\omega^2 A \sin(\omega t + \phi)$$

Therefore:

$$v_{\max} = \omega A$$

$$a_{\max} = \omega^2 A$$

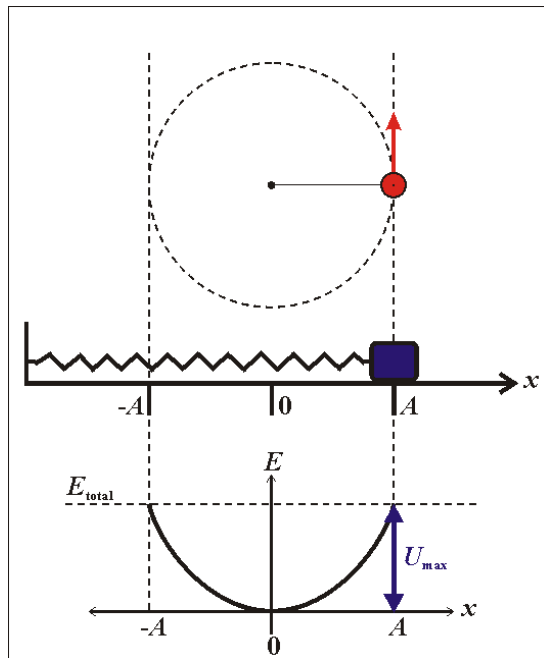


# Putting it all together: The bottom line

$$acc + (const)(displacement) = 0$$

$$[-\omega^2 A \sin(\omega t + \phi) + \left(\frac{k}{m}\right) A \sin(\omega t + \phi) = 0$$

$$\omega^2 = \frac{k}{m}, \omega = \sqrt{\frac{k}{m}}$$



$$v = \frac{2\pi r}{T}$$

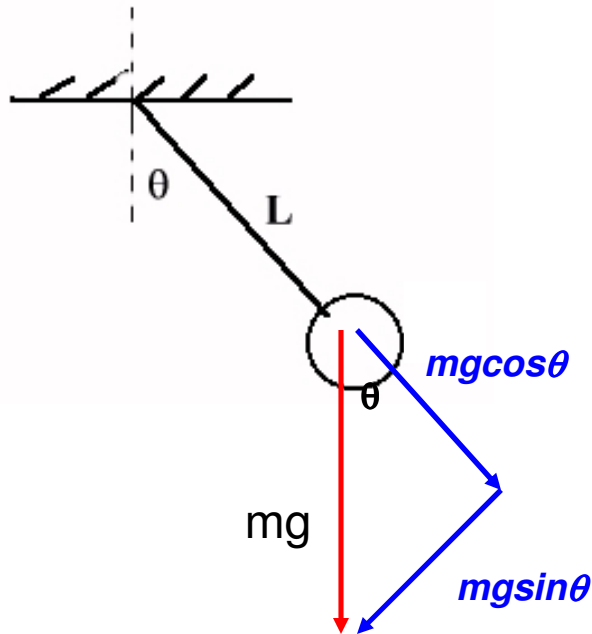
$$v = r\omega, \omega = \frac{v}{r}$$

$$\omega = \frac{2\pi}{T}$$

$$T_{spring} = \frac{2\pi}{\omega} = \frac{2\pi}{\sqrt{\frac{k}{m}}} = 2\pi \sqrt{\frac{m}{k}}$$

Since all springs exhibit properties of circle motion we can use these expressions to derive the formula for the **period of a spring**.

# The simple pendulum



$$Fr \sin \theta = \tau = I\alpha$$

$$-mg \sin \theta(L) = (mL^2)\alpha$$

$$-g \sin \theta = L\alpha \quad \text{if } \theta \ll \ll, \sin \theta = \theta$$

$$\alpha + \left(\frac{g}{L}\right)\theta = 0$$

$$\omega = \sqrt{\frac{g}{L}}, \quad \omega = \frac{2\pi}{T}$$

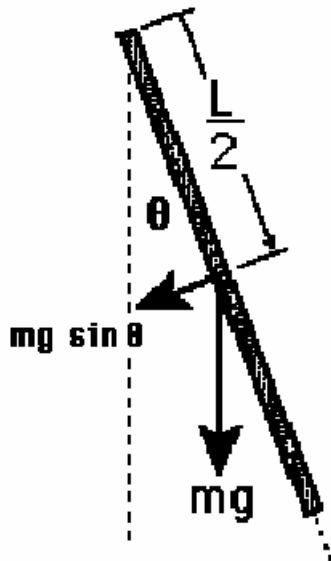
$$T_{\text{pendulum}} = 2\pi \sqrt{\frac{l}{g}}$$

If the angle is small, the "radian" value for theta and the sine of the theta in degrees will be equal.

A simple pendulum is one where a mass is located at the end of string. The string's length represents the radius of a circle and has negligible mass.

Once again, using our sine function model we can derive using circular motion equations the formula for the period of a pendulum.

# The Physical Pendulum



A physical pendulum is an oscillating body that rotates according to the location of its center of mass rather than a simple pendulum where all the mass is located at the end of a light string.

$$Fr \sin \theta = \tau = I\alpha$$

$$-mg \sin \theta d = I\alpha, \quad d = L/2$$

$$-mgd = I\alpha \quad \text{if } \theta \ll \ll, \sin \theta = \theta$$

$$\alpha + \left(\frac{mgd}{I}\right)\theta = 0$$

$$\omega = \sqrt{\frac{mgd}{I}}, \quad \omega = \frac{2\pi}{T}$$

$$T_{\text{physical pendulum}} = 2\pi \sqrt{\frac{I}{mgd}}$$

**It is important to understand that “d” is the lever arm distance or the distance from the COM position to the point of rotation.** It is also the same “d” in the Parallel Axes theorem.



## Example

A spring is hanging from the ceiling. You know that if you elongate the spring by 3.0 meters, it will take 330 N of force to hold it at that position: The spring is then hung and a 5.0-kg mass is attached. The system is allowed to reach equilibrium; then displaced an additional 1.5 meters and released. Calculate the:

Spring Constant  $F_s = kx \quad 330 = (k)(3)$

$$k = 110 \text{ N/m}$$

Angular frequency  $\omega^2 = \frac{k}{m} \quad \omega = \sqrt{\frac{k}{m}} = \sqrt{\frac{110}{5}} = 4.7 \text{ rad/s}$

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**Amplitude**      **Stated in the question as 1.5 m**

$$\omega = 2\pi f = \frac{2\pi}{T}$$

**Frequency and Period**

$$f = \frac{\omega}{2\pi} = \frac{4.7}{2\pi} = \mathbf{0.75 \text{ Hz}}$$

$$T = \frac{2\pi}{\omega} = \frac{2\pi}{4.7} = \mathbf{1.34 \text{ s}}$$

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**Total Energy**  $U_s = \frac{1}{2} kx^2 = \frac{1}{2} kA^2$

$$U = \frac{1}{2} (110)(1.5)^2 = \mathbf{123.75 \text{ J}}$$

**Maximum velocity**  $v = A\omega = (1.5)(4.7) = \mathbf{7.05 \text{ m/s}}$

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**Position of mass at maximum velocity**      **At the equilibrium position**

**Maximum acceleration of the mass**

$$a = \omega^2 A = (4.7)^2 (1.5) = 33.135 \text{ m/s/s}$$

**Position of mass at maximum acceleration**

**At maximum amplitude, 1.5 m**

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