## **AP® PHYSICS 1 TABLE OF INFORMATION**

CONSTANTS AND CONVERSION FACTORS							
Proton mass, $m_p = 1.67 \times 10^{-27}$ kg	Electron charge magnitude,	$e = 1.60 \times 10^{-19} \text{ C}$					
Neutron mass, $m_n = 1.67 \times 10^{-27}$ kg	Coulomb's law constant,	$k = 1/4\pi\varepsilon_0 = 9.0 \times 10^9 \text{ N} \cdot \text{m}^2/\text{C}^2$					
Electron mass, $m_e = 9.11 \times 10^{-31}$ kg	Universal gravitational constant,	$G = 6.67 \times 10^{-11} \text{ m}^3/\text{kg}\cdot\text{s}^2$					
Speed of light, $c = 3.00 \times 10^8 \text{ m/s}$	Acceleration due to gravity at Earth's surface,	$g = 9.8 \text{ m/s}^2$					

	meter,	m	kelvin,	Κ	watt,	W	degree Celsius,	°C
UNIT	kilogram,	kg	hertz,	Hz	coulomb,	С		
SYMBOLS	second,	S	newton,	Ν	volt,	V		
	ampere,	А	joule,	J	ohm,	Ω		

VALUES OF TRIGONOMETRIC FUNC							CTIONS FOR COMMON ANGLES			
nbol F		θ	$0^{\circ}$	$30^{\circ}$	$37^{\circ}$	$45^{\circ}$	$53^{\circ}$	$60^{\circ}$	$90^{\circ}$	
Ĵ		sin <del>0</del>	0	1/2	3/5	$\sqrt{2}/2$	4/5	$\sqrt{3}/2$	1	
Л		$\cos \theta$	1	$\sqrt{3}/2$	4/5	$\sqrt{2}/2$	3/5	1/2	0	
K.		tan <del>0</del>	0	$\sqrt{3}/3$	3/4	1	4/3	$\sqrt{3}$	8	
c				•	•	•				

The following conventions are used in this exam.

- I. The frame of reference of any problem is assumed to be inertial unless otherwise stated.
- II. Assume air resistance is negligible unless otherwise stated.
- III. In all situations, positive work is defined as work done <u>on</u> a system.
- IV. The direction of current is conventional current: the direction in which positive charge would drift.
- V. Assume all batteries and meters are ideal unless otherwise stated.

PREFIXES					
Factor	Prefix	Symbol			
10 <sup>12</sup>	tera	Т			
10 <sup>9</sup>	giga	G			
$10^{6}$	mega	М			
10 <sup>3</sup>	kilo	k			
$10^{-2}$	centi	с			
$10^{-3}$	milli	m			
$10^{-6}$	micro	μ			
$10^{-9}$	nano	n			
10 <sup>-12</sup>	pico	р			

$\begin{array}{c} v_{x} = v_{x0} + a_{xl} & a = \operatorname{acceleration} \\ A = \operatorname{amplitude} \\ x = x_{0} + v_{x0}t + \frac{1}{2}a_{xl}t^{2} & E = \operatorname{energy} \\ d = \operatorname{distance} \\ x = x_{0} + v_{x0}t + \frac{1}{2}a_{xl}t^{2} & E = \operatorname{energy} \\ v_{x}^{2} = v_{x0}^{2} + 2a_{x}(x - x_{0}) & f = \operatorname{force} \\ d = \underline{\sum \vec{F}} = \frac{\vec{F}_{ner}}{m} & K = \operatorname{kinic c energy} \\ k = \operatorname{spring constant} \\  \vec{F}_{l}  \leq \mu  \vec{F}_{n}  & L = \operatorname{angular momentum} \\ d =  ength \\ a_{c} = \frac{v^{2}}{r} & P = \operatorname{power} \\ \vec{p} = m\dot{v} & r = \operatorname{separation} \\ \lambda \phi = \vec{F} \Delta t & T = \operatorname{priod} \\ \Delta E = W = F_{  }d = Fd \cos \theta & v = \operatorname{speed} \\ \Delta E = W = F_{  }d = Fd \cos \theta & v = \operatorname{speed} \\ M = \operatorname{volume} \\ d = angular acceleration \\ \theta = \theta_{0} + a_{0}t + \frac{1}{2}\alpha t^{2} & \mu = \operatorname{coefficient of friction} \\ \theta = \theta_{0} + a_{0}t + \frac{1}{2}\alpha t^{2} & \mu = \operatorname{coefficient of friction} \\ \theta = \theta_{0} + a_{0}t + \frac{1}{2}\alpha t^{2} & \mu = \operatorname{coefficient of friction} \\ \theta = \theta_{0} + a_{0}t + \frac{1}{2}\alpha t^{2} & \mu = \operatorname{coefficient of friction} \\ \theta = a_{0} + at & r = \operatorname{torque} \\ x = r_{1}E = r_{1}E = r_{1}E \\ \Delta L = r\Delta & T_{1} = 2\pi \sqrt{\frac{T}{k}} \\ K = \frac{1}{2}Ia^{2} & T_{1} = 2\pi \sqrt{\frac{T}{k}} \\ K = \frac{1}{2}Ia^{2} & T_{1} = 2\pi \sqrt{\frac{T}{k}} \\ k = \frac{1}{k} = G \frac{m_{1}m_{2}}{r^{2}} \\ u_{1} = \frac{1}{k} = G \frac{m_{1}m_{2}}{r^{2}} \\ u_{2} = \frac{1}{k} = \frac{1}{k} \\ Retangular sociel and \\ Retangular acceleration \\ \theta = \theta_{0} + adt & r = \operatorname{torque} \\ \theta = \operatorname{angular acceleration} \\ \theta = \theta_{0} + adt & r = \operatorname{torque} \\ \pi = r_{1} = \frac{1}{r} \\ \Delta L = r\Delta & T_{1} = 2\pi \sqrt{\frac{T}{k}} \\ K = \frac{1}{2}Ia^{2} & T_{1} = 2\pi \sqrt{\frac{T}{k}} \\ K = \frac{1}{2}Ia^{2} & T_{1} = 2\pi \sqrt{\frac{T}{k}} \\ \vec{F}_{k}   = k  \vec{R}_{k}   \vec{F}_{k}   = \frac{m_{1}m_{2}}{r^{2}} \\ u_{k} = \frac{1}{r} \\ \vec{F}_{k}   = \frac{m_{1}m_{2}}{r^{2}} \\ u_{k} = \frac{1}{r} \\ \frac{1}{r} = \frac{\pi}{n} \\ \frac$	MECH	IANICS	ELECTRICITY		
$U_{s} = \frac{1}{2}kx^{2}$ $\vec{g} = \frac{\vec{F}_{g}}{m}$ Sphere $V = \frac{4}{3}\pi r^{3}$ $\vec{\theta} = \frac{90^{\circ}}{h}$	$v_{x} = v_{x0} + a_{x}t$ $x = x_{0} + v_{x0}t + \frac{1}{2}a_{x}t^{2}$ $v_{x}^{2} = v_{x0}^{2} + 2a_{x}(x - x_{0})$ $\vec{a} = \frac{\sum \vec{F}}{m} = \frac{\vec{F}_{net}}{m}$ $ \vec{F}_{f}  \le \mu  \vec{F}_{n} $ $a_{c} = \frac{v^{2}}{r}$ $\vec{p} = m\vec{v}$ $\Delta \vec{p} = \vec{F} \Delta t$ $K = \frac{1}{2}mv^{2}$ $\Delta E = W = F_{\parallel}d = Fd\cos\theta$ $P = \frac{\Delta E}{\Delta t}$ $\theta = \theta_{0} + \omega_{0}t + \frac{1}{2}\alpha t^{2}$ $\omega = \omega_{0} + \alpha t$ $x = A\cos(2\pi ft)$ $\vec{\alpha} = \frac{\sum \vec{\tau}}{I} = \frac{\vec{\tau}_{net}}{I}$ $\tau = r_{\perp}F = rF\sin\theta$ $L = I\omega$ $\Delta L = \tau \Delta t$ $K = \frac{1}{2}I\omega^{2}$	$a = \operatorname{acceleration} A$ $= \operatorname{amplitude} d$ $d = \operatorname{distance} E$ $E = \operatorname{energy} f$ $f = \operatorname{frequency} F$ $F = \operatorname{force} I$ $I = \operatorname{rotational inertia} K$ $K = \operatorname{kinetic energy} k$ $k = \operatorname{spring constant} L$ $L = \operatorname{angular momentum} \ell$ $\ell = \operatorname{length} m$ $m = \operatorname{mass} P$ $P = \operatorname{power} p$ $p = \operatorname{momentum} r$ $r = \operatorname{radius or separation} T$ $T = \operatorname{period} t$ $t = \operatorname{time} U$ $U = \operatorname{potential energy} V$ $V = \operatorname{volume} v$ $v = \operatorname{speed} W$ $W = \operatorname{work done on a system} x$ $x = \operatorname{position} y$ $y = \operatorname{height} \alpha = \operatorname{angular acceleration} \mu$ $\mu = \operatorname{coefficient of friction} \theta$ $\theta = \operatorname{angle} \rho$ $\rho = \operatorname{density} \tau$ $\tau = \operatorname{torque} \omega$ $\omega = \operatorname{angular speed} \Delta U_g = mg \Delta y$ $T = \frac{2\pi}{\omega} = \frac{1}{f}$ $T_p = 2\pi \sqrt{\frac{\ell}{g}}$	$\begin{aligned} \left  \vec{F}_{E} \right  &= k \left  \frac{q_{1}q_{2}}{r^{2}} \right  \\ I &= \frac{\Delta q}{\Delta t} \\ R &= \frac{\rho \ell}{A} \\ I &= \frac{\Delta V}{R} \\ P &= I \Delta V \\ R_{s} &= \sum_{i} R_{i} \\ \frac{1}{R_{p}} &= \sum_{i} \frac{1}{R_{i}} \\ \hline \mathbf{V} \\ \lambda &= \frac{v}{f} \qquad \begin{array}{c} \mathbf{V} \\ \mathbf{v} \\ \mathbf{k} \\$	$A = \text{area}$ $F = \text{force}$ $I = \text{current}$ $\ell = \text{length}$ $P = \text{power}$ $q = \text{charge}$ $R = \text{resistance}$ $r = \text{separation}$ $t = \text{time}$ $V = \text{electric potential}$ $\rho = \text{resistivity}$ $VAVES$ $= \text{frequency}$ $= \text{speed}$ $= \text{wavelength}$ $VD TRIGONOMETRY$ $A = \text{area}$ $C = \text{circumference}$ $V = \text{volume}$ $S = \text{surface area}$ $b = \text{base}$ $h = \text{height}$ $\ell = \text{length}$ $w = \text{width}$ $r = \text{radius}$ $Right triangle$ $c^2 = a^2 + b^2$ $\sin \theta = \frac{a}{c}$ $\cos \theta = \frac{b}{c}$	
o r	$U_s = \frac{1}{2}kx^2$	1	Sphere	$\frac{c}{1\theta} 90^{\circ}_{\Box}a$	