AP® Physics C: Mechanics
2015 Free-Response Questions

ADVANCED PLACEMENT PHYSICS C TABLE OF INFORMATION

CONSTANTS AND CONVERSION FACTORS			
Proton mass,	$m_p = 1.67 \times 10^{-27}$ kg	Electron charge magnitude,	$e = 1.60 \times 10^{-19}$ C
Neutron mass,	$m_n = 1.67 \times 10^{-27}$ kg	1 electron volt,	$1 \text{ eV} = 1.60 \times 10^{-19}$ J
Electron mass,	$m_e = 9.11 \times 10^{-31}$ kg	Speed of light,	$c = 3.00 \times 10^{8}$ m/s
Avogadro's number,	$N_0 = 6.02 \times 10^{23} \text{ mol}^{-1}$	Universal gravitational constant,	$G = 6.67 \times 10^{-11} \left(\text{N}\cdot\text{m}^2\right)/\text{kg}^2$
Universal gas constant,	$R = 8.31$ J/(mol•K)	Acceleration due to gravity at Earth's surface,	$g = 9.8 \text{ m/s}^2$
Boltzmann's constant,	$k_B = 1.38 \times 10^{-23}$ J/K		

1 unified atomic mass unit,	$1 \text{ u} = 1.66 \times 10^{-27} \text{ kg} = 931 \text{ MeV}/c^2$
Planck's constant,	$h = 6.63 \times 10^{-34} \text{ J}\cdot\text{s} = 4.14 \times 10^{-15} \text{ eV}\cdot\text{s}$
	$hc = 1.99 \times 10^{-25} \text{ J}\cdot\text{m} = 1.24 \times 10^{3} \text{ eV}\cdot\text{nm}$
Vacuum permittivity,	$\varepsilon_0 = 8.85 \times 10^{-12} \text{ C}^2/\left(\text{N}\cdot\text{m}^2\right)$
Coulomb's law constant,	$k = 1/(4\pi\varepsilon_0) = 9.0 \times 10^{9} \left(\text{N}\cdot\text{m}^2\right)/\text{C}^2$
Vacuum permeability,	$\mu_0 = 4\pi \times 10^{-7}$ (T•m)/A
Magnetic constant,	$k' = \mu_0/(4\pi) = 1 \times 10^{-7}$ (T•m)/A
1 atmosphere pressure,	$1 \text{ atm} = 1.0 \times 10^{5} \text{ N/m}^2 = 1.0 \times 10^{5}$ Pa

UNIT SYMBOLS								
	meter,	m	mole,	mol	watt,	W	farad,	F
	kilogram,	kg	hertz,	Hz	coulomb,	C	tesla,	T
	second,	s	newton,	N	volt,	V	degree Celsius,	°C
	ampere,	A	pascal,	Pa	ohm,	Ω	electron volt,	eV
	kelvin,	K	joule,	J	henry,	H		

PREFIXES		
Factor	Prefix	Symbol
10^{9}	giga	G
10^{6}	mega	M
10^{3}	kilo	k
10^{-2}	centi	c
10^{-3}	milli	m
10^{-6}	micro	μ
10^{-9}	nano	n
10^{-12}	pico	p

VALUES OF TRIGONOMETRIC FUNCTIONS FOR COMMON ANGLES							
θ	0°	30°	37°	45°	53°	60°	90°
$\sin\theta$	0	$1/2$	$3/5$	$\sqrt{2}/2$	$4/5$	$\sqrt{3}/2$	1
$\cos\theta$	1	$\sqrt{3}/2$	$4/5$	$\sqrt{2}/2$	$3/5$	$1/2$	0
$\tan\theta$	0	$\sqrt{3}/3$	$3/4$	1	$4/3$	$\sqrt{3}$	∞

The following assumptions are used in this exam.

I. The frame of reference of any problem is inertial unless otherwise stated.
II. The direction of current is the direction in which positive charges would drift.
III. The electric potential is zero at an infinite distance from an isolated point charge.
IV. All batteries and meters are ideal unless otherwise stated.
V. Edge effects for the electric field of a parallel plate capacitor are negligible unless otherwise stated.

ADVANCED PLACEMENT PHYSICS C EQUATIONS

MECHANICS

$v_x = v_{x0} + a_x t$

$x = x_0 + v_{x0} t + \frac{1}{2} a_x t^2$

$v_x^2 = v_{x0}^2 + 2a_x (x - x_0)$

$\vec{a} = \frac{\sum \vec{F}}{m} = \frac{\vec{F}_{net}}{m}$

$\vec{F} = \frac{d\vec{p}}{dt}$

$\vec{J} = \int \vec{F}\, dt = \Delta \vec{p}$

$\vec{p} = m\vec{v}$

$\left|\vec{F}_f\right| \le \mu \left|\vec{F}_N\right|$

$\Delta E = W = \int \vec{F} \cdot d\vec{r}$

$K = \frac{1}{2} m v^2$

$P = \frac{dE}{dt}$

$P = \vec{F} \cdot \vec{v}$

$\Delta U_g = mg\Delta h$

$a_c = \frac{v^2}{r} = \omega^2 r$

$\vec{\tau} = \vec{r} \times \vec{F}$

$\vec{\alpha} = \frac{\sum \vec{\tau}}{I} = \frac{\vec{\tau}_{net}}{I}$

$I = \int r^2 dm = \sum m r^2$

$x_{cm} = \frac{\sum m_i x_i}{\sum m_i}$

$v = r\omega$

$\vec{L} = \vec{r} \times \vec{p} = I\vec{\omega}$

$K = \frac{1}{2} I \omega^2$

$\omega = \omega_0 + \alpha t$

$\theta = \theta_0 + \omega_0 t + \frac{1}{2} \alpha t^2$

a = acceleration
E = energy
F = force
f = frequency
h = height
I = rotational inertia
J = impulse
K = kinetic energy
k = spring constant
ℓ = length
L = angular momentum
m = mass
P = power
p = momentum
r = radius or distance
T = period
t = time
U = potential energy
v = velocity or speed
W = work done on a system
x = position
μ = coefficient of friction
θ = angle
τ = torque
ω = angular speed
α = angular acceleration
ϕ = phase angle

$\vec{F}_s = -k\Delta\vec{x}$

$U_s = \frac{1}{2} k (\Delta x)^2$

$x = x_{\max} \cos(\omega t + \phi)$

$T = \frac{2\pi}{\omega} = \frac{1}{f}$

$T_s = 2\pi \sqrt{\frac{m}{k}}$

$T_p = 2\pi \sqrt{\frac{\ell}{g}}$

$\left|\vec{F}_G\right| = \frac{G m_1 m_2}{r^2}$

$U_G = -\frac{G m_1 m_2}{r}$

ELECTRICITY AND MAGNETISM

$\left|\vec{F}_E\right| = \frac{1}{4\pi\varepsilon_0} \left|\frac{q_1 q_2}{r^2}\right|$

$\vec{E} = \frac{\vec{F}_E}{q}$

$\oint \vec{E} \cdot d\vec{A} = \frac{Q}{\varepsilon_0}$

$E_x = -\frac{dV}{dx}$

$\Delta V = -\int \vec{E} \cdot d\vec{r}$

$V = \frac{1}{4\pi\varepsilon_0} \sum_i \frac{q_i}{r_i}$

$U_E = qV = \frac{1}{4\pi\varepsilon_0} \frac{q_1 q_2}{r}$

$\Delta V = \frac{Q}{C}$

$C = \frac{\kappa \varepsilon_0 A}{d}$

$C_p = \sum_i C_i$

$\frac{1}{C_s} = \sum_i \frac{1}{C_i}$

$I = \frac{dQ}{dt}$

$U_C = \frac{1}{2} Q \Delta V = \frac{1}{2} C (\Delta V)^2$

$R = \frac{\rho \ell}{A}$

$\vec{E} = \rho \vec{J}$

$I = N e v_d A$

$I = \frac{\Delta V}{R}$

$R_s = \sum_i R_i$

$\frac{1}{R_p} = \sum_i \frac{1}{R_i}$

$P = I\Delta V$

A = area
B = magnetic field
C = capacitance
d = distance
E = electric field
$\mathcal{E}$ = emf
F = force
I = current
J = current density
L = inductance
ℓ = length
n = number of loops of wire per unit length
N = number of charge carriers per unit volume
P = power
Q = charge
q = point charge
R = resistance
r = radius or distance
t = time
U = potential or stored energy
V = electric potential
v = velocity or speed
ρ = resistivity
Φ = flux
κ = dielectric constant

$\vec{F}_M = q\vec{v} \times \vec{B}$

$\oint \vec{B} \cdot d\vec{\ell} = \mu_0 I$

$d\vec{B} = \frac{\mu_0}{4\pi} \frac{I\, d\vec{\ell} \times \hat{r}}{r^2}$

$\vec{F} = \int I\, d\vec{\ell} \times \vec{B}$

$B_s = \mu_0 n I$

$\Phi_B = \int \vec{B} \cdot d\vec{A}$

$\mathcal{E} = \oint \vec{E} \cdot d\vec{\ell} = -\frac{d\Phi_B}{dt}$

$\mathcal{E} = -L\frac{dI}{dt}$

$U_L = \frac{1}{2} L I^2$

GEOMETRY AND TRIGONOMETRY

Rectangle

$A = bh$

Triangle

$A = \frac{1}{2}bh$

Circle

$A = \pi r^2$

$C = 2\pi r$

$s = r\theta$

Rectangular Solid

$V = \ell wh$

Cylinder

$V = \pi r^2 \ell$

$S = 2\pi r\ell + 2\pi r^2$

Sphere

$V = \frac{4}{3}\pi r^3$

$S = 4\pi r^2$

A = area

C = circumference

V = volume

S = surface area

b = base

h = height

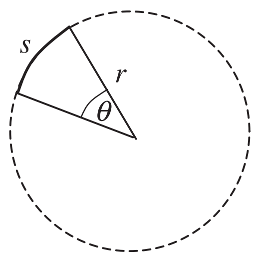
ℓ = length

w = width

r = radius

s = arc length

θ = angle



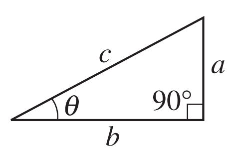
Right Triangle

$a^2 + b^2 = c^2$

$\sin\theta = \frac{a}{c}$

$\cos\theta = \frac{b}{c}$

$\tan\theta = \frac{a}{b}$



CALCULUS

$$\frac{df}{dx} = \frac{df}{du}\frac{du}{dx}$$

$$\frac{d}{dx}\left(x^n\right) = nx^{n-1}$$

$$\frac{d}{dx}\left(e^{ax}\right) = ae^{ax}$$

$$\frac{d}{dx}(\ln ax) = \frac{1}{x}$$

$$\frac{d}{dx}[\sin(ax)] = a\cos(ax)$$

$$\frac{d}{dx}[\cos(ax)] = -a\sin(ax)$$

$$\int x^n\,dx = \frac{1}{n+1}x^{n+1},\ n \neq -1$$

$$\int e^{ax}\,dx = \frac{1}{a}e^{ax}$$

$$\int \frac{dx}{x+a} = \ln|x+a|$$

$$\int \cos(ax)\,dx = \frac{1}{a}\sin(ax)$$

$$\int \sin(ax)\,dx = -\frac{1}{a}\cos(ax)$$

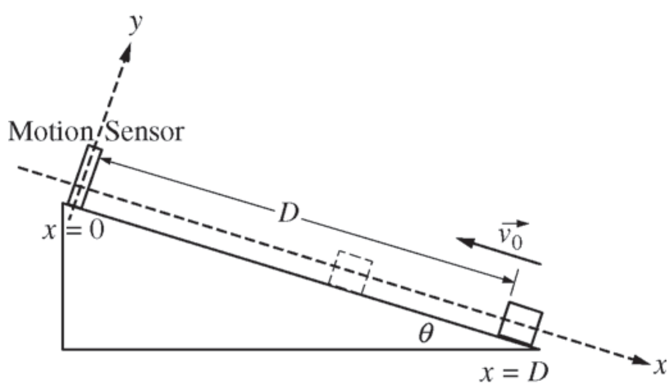
VECTOR PRODUCTS

$\vec{A}\bullet\vec{B} = AB\cos\theta$

$\left|\vec{A}\times\vec{B}\right| = AB\sin\theta$

PHYSICS C: MECHANICS
SECTION II
Time—45 minutes
3 Questions

Directions: Answer all three questions. The suggested time is about 15 minutes for answering each of the questions, which are worth 15 points each. The parts within a question may not have equal weight. Show all your work in this booklet in the spaces provided after each part.



Mech.1.

A block of mass m is projected up from the bottom of an inclined ramp with an initial velocity of magnitude v_0. The ramp has negligible friction and makes an angle θ with the horizontal. A motion sensor aimed down the ramp is mounted at the top of the incline so that the positive direction is down the ramp. The block starts a distance D from the motion sensor, as shown above. The block slides partway up the ramp, stops before reaching the sensor, and then slides back down.

(a) Consider the motion of the block at some time t after it has been projected up the ramp. Express your answers in terms of m, D, v_0, t, θ and physical constants, as appropriate.

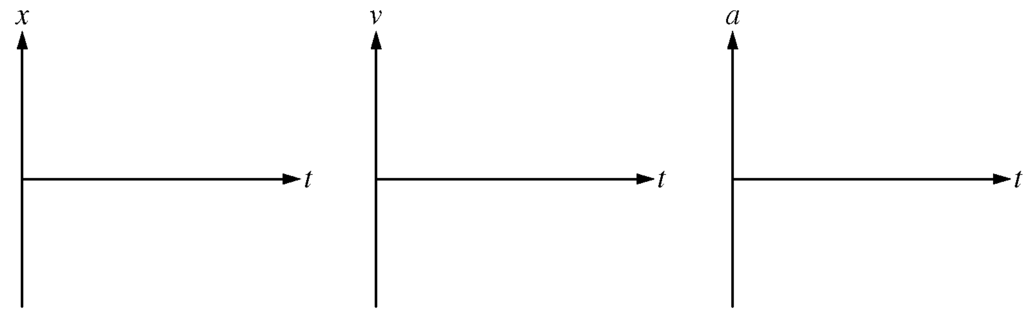
i. Determine the acceleration a of the block.

ii. Determine an expression for the velocity v of the block.

iii. Determine an expression for the position x of the block.

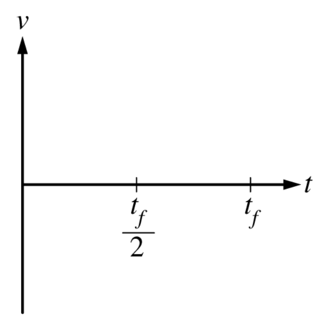
(b) Derive an expression for the position x_{min} of the block when it is closest to the motion sensor. Express your answer in terms of m, D, v_0, θ, and physical constants, as appropriate.

(c) On the axes provided below, sketch graphs of position x, velocity v, and acceleration a as functions of time t for the motion of the block while it goes up and back down the ramp. Explicitly label any intercepts, asymptotes, maxima, or minima with numerical values or algebraic expressions, as appropriate.



(d) After the block slides back down and leaves the bottom of the ramp, it slides on a horizontal surface with a coefficient of friction given by μ_k. Derive an expression for the distance the block slides before stopping. Express your answer in terms of m, D, v_0, θ, μ_k, and physical constants, as appropriate.

(e) Suppose the ramp now has friction. The same block is projected up with the same initial speed v_0 and comes back down the ramp. On the axes provided below, sketch a graph of the velocity v as a function of time t for the motion of the block while it goes up and back down the ramp, arriving at the bottom of the ramp at time t_f. Explicitly label any intercepts, asymptotes, maxima, or minima with numerical values or algebraic expressions, as appropriate.



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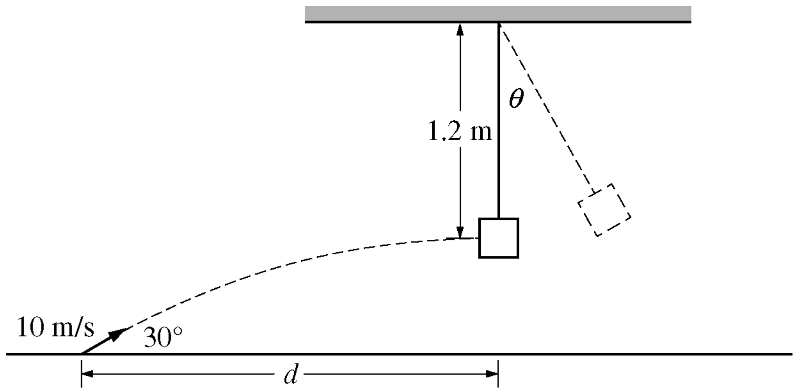

Mech.2.

A small dart of mass 0.020 kg is launched at an angle of 30° above the horizontal with an initial speed of 10 m/s. At the moment it reaches the highest point in its path and is moving horizontally, it collides with and sticks to a wooden block of mass 0.10 kg that is suspended at the end of a massless string. The center of mass of the block is 1.2 m below the pivot point of the string. The block and dart then swing up until the string makes an angle θ with the vertical, as shown above. Air resistance is negligible.

(a) Determine the speed of the dart just before it strikes the block.

(b) Calculate the horizontal distance d between the launching point of the dart and a point on the floor directly below the block.

(c) Calculate the speed of the block just after the dart strikes.

(d) Calculate the angle θ through which the dart and block on the string will rise before coming momentarily to rest.

(e) The block then continues to swing as a simple pendulum. Calculate the time between when the dart collides with the block and when the block first returns to its original position.

(f) In a second experiment, a dart with more mass is launched at the same speed and angle. The dart collides with and sticks to the same wooden block.

i. Would the angle θ that the dart and block swing to increase, decrease, or stay the same?

_____ Increase _____ Decrease _____ Stay the same

Justify your answer.

ii. Would the period of oscillation after the collision increase, decrease, or stay the same?

_____ Increase _____ Decrease _____ Stay the same

Justify your answer.

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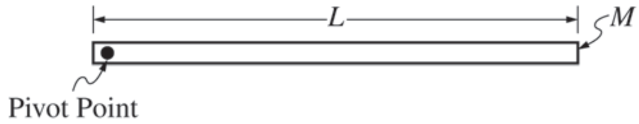
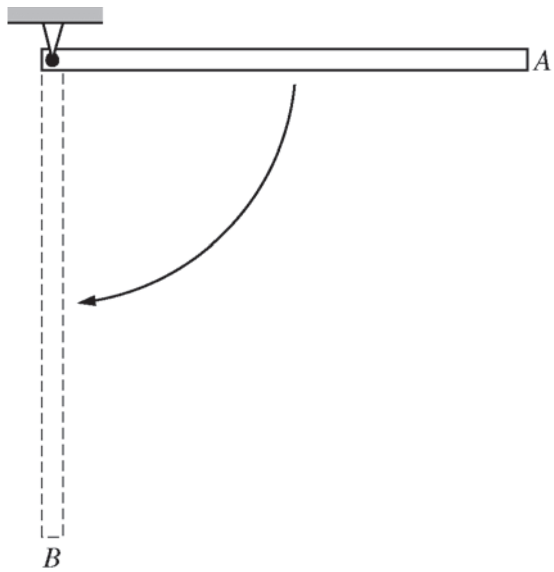


Mech.3.

A uniform, thin rod of length L and mass M is allowed to pivot about its end, as shown in the figure above.

(a) Using integral calculus, derive the rotational inertia for the rod around its end to show that it is $ML^2/3$.



The rod is fixed at one end and allowed to fall from the horizontal position A through the vertical position B.

(b) Derive an expression for the velocity of the free end of the rod at position B. Express your answer in terms of M, L, and physical constants, as appropriate.

An experiment is designed to test the validity of the expression found in part (b). A student uses rods of various lengths that all have a uniform mass distribution. The student releases each of the rods from the horizontal position A and uses photogates to measure the velocity of the free end at position B. The data are recorded below.

Length (m)	0.25	0.50	0.75	1.00	1.25	1.50
Velocity (m/s)	2.7	3.8	4.6	5.2	5.8	6.3

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(c) Indicate below which quantities should be graphed to yield a straight line whose slope could be used to calculate a numerical value for the acceleration due to gravity g.

Horizontal axis: ____________________

Vertical axis: ____________________

Use the remaining rows in the table above, as needed, to record any quantities that you indicated that are not given. Label each row you use and include units.

(d) Plot the straight line data points on the grid below. Clearly scale and label all axes, including units as appropriate. Draw a straight line that best represents the data.

(e)

i. Using your straight line, determine an experimental value for g.

ii. Describe two ways in which the effects of air resistance could be reduced.

STOP

END OF EXAM